BRL Seminar

(2024.01.03.Wed)

Diffusion Model with Time Series Data

통합과정 7학기 이승한

Contents

- Preliminaries: Diffusion Model
- 2. Conditional Time-series Diffusion Model: TimeGrad, CSDI
- 3. Unconditional Time-series Diffusion Model: TSDiff

Papers

Conditional / Unconditional diffusion model

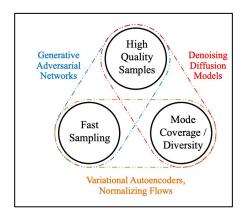
- [TimeGrad] Autoregressive Denoising Diffusion Models for Multivariate Probabilistic Time Series Forecasting (ICML, 2021)
 - https://arxiv.org/pdf/2101.12072.pdf
- 2. [CSDI] Conditional Score-based Diffusion Models for Probabilistic Time Series Imputation (NeurIPS 2021)
 - https://arxiv.org/pdf/2107.03502.pdf
- [TSDiff] Non-autoregressive Conditional Diffusion Models for Time Series Prediction (NeurIPS 2023) 3.

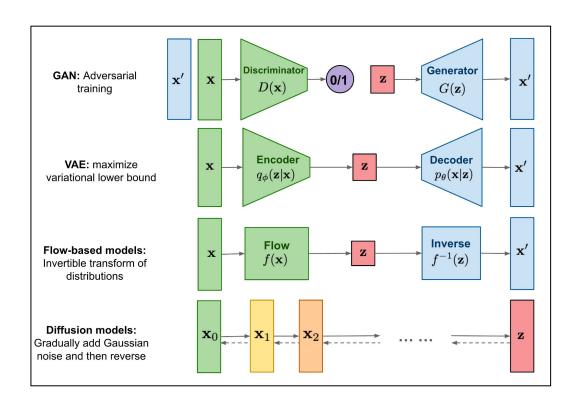


https://arxiv.org/pdf/2307.11494.pdf

1-1. Generative Models

- (1) GAN
- (2) Diffusion
- (3) VAE, Normalizing Flows

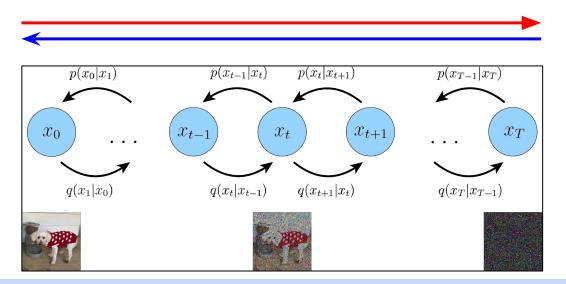




1-2. Diffusion Model

Forward Process: Add Noise

Backward Process: Remove Noise



1-2. Diffusion Model

- Forward Process: Add Noise

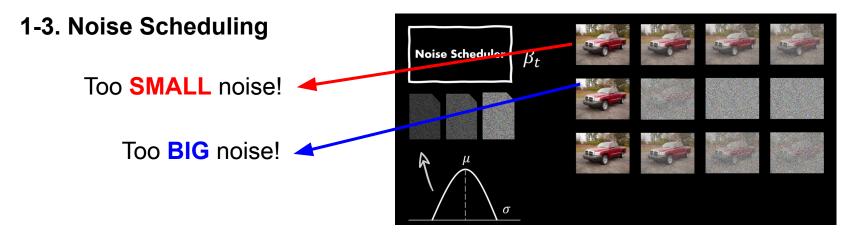
$$q\left(\mathbf{x}_{t} \mid \mathbf{x}_{t-1}\right) = N\left(\mathbf{x}_{t}; \sqrt{1 - \beta_{t}} \mathbf{x}_{t-1}, \beta_{t} \mathbf{I}\right)$$

Backward Process: Remove Noise

$$p_{\theta} (\mathbf{x}_{t-1} \mid \mathbf{x}_t) = N (\mathbf{x}_{t-1}; \mu_{\theta} (\mathbf{x}_t, t), \Sigma_{\theta} (\mathbf{x}_t, t))$$

 eta_t controls the strength of the noise ightarrow Noise Scheduling

ex) DDPM: Linear Scheduling $T=1000, eta_0=0.0001, eta_{1000}=0.02$



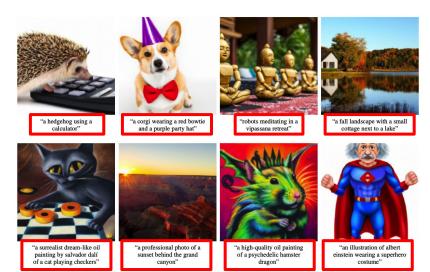
Linear scheduler
Cosine scheduler



Linear (top) vs Cosine (bottom)

1-4. Conditional Diffusion Model

- Unconditional Diffusion Model: "Draw a picture"
- Conditional Diffusion Model: "Draw a picture of a dog"



Anything can be a condition!

https://arxiv.org/abs/2112.10741

1-4. Conditional Diffusion Model

How to guide the diffusion model under certain condition?

- (1) Classifier guidance (CG): w/ classifier
- (2) Classifier-free guidance (CFG): w/o classifier

1-4. Conditional Diffusion Model

How to guide the diffusion model under certain condition?

- (1) Classifier guidance (CG): w/ classifier

$$\frac{\nabla \log p\left(\mathbf{x}_{t} \mid y\right)}{\operatorname{\textbf{Conditional Score}}} = \nabla \log \left(\frac{p\left(\mathbf{x}_{t}\right)p\left(y \mid \mathbf{x}_{t}\right)}{p(y)}\right)$$

$$(Score of \mathbf{x}_{t}, under condition \mathbf{y}) = \nabla \log p\left(\mathbf{x}_{t}\right) + \nabla \log p\left(y \mid \mathbf{x}_{t}\right) - \nabla \log p(y)$$

$$= \nabla \log p\left(\mathbf{x}_{t}\right) + \gamma \nabla \log p\left(y \mid \mathbf{x}_{t}\right) - \nabla \log p(y)$$

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1-4. Conditional Diffusion Model

$$\nabla \log p\left(\mathbf{x}_{t} \mid y\right) = \nabla \log \left(\frac{p\left(\mathbf{x}_{t}\right) p\left(y \mid \mathbf{x}_{t}\right)}{p(y)}\right)$$

unconditional score

How to guide the diffusion model under certain condition?

$$= \nabla \log p(\mathbf{x}_t) + \nabla \log p(y \mid \mathbf{x}_t) - \nabla \log p(y)$$

$$= \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(y \mid \mathbf{x}_t)$$

adversarial gradient

- (1) Classifier guidance (CG): w/ classifier

Algorithm 1 Classifier guided diffusion sampling, given a diffusion model $(\mu_{\theta}(x_t), \Sigma_{\theta}(x_t))$, classifier $p_{\phi}(y|x_t)$, and gradient scale s.

```
Input: class label y, gradient scale s x_T \leftarrow \text{sample from } \mathcal{N}(0, \mathbf{I}) for all t from T to 1 do \mu, \Sigma \leftarrow \mu_{\theta}(x_t), \Sigma_{\theta}(x_t) Guidance x_{t-1} \leftarrow \text{sample from } \mathcal{N}(\mu + s\Sigma \nabla_{x_t} \log p_{\phi}(y|x_t), \Sigma) end for return x_0
```

1-4. Conditional Diffusion Model

How to guide the diffusion model under certain condition?

- (2) Classifier-free guidance (CFG): w/o classifier

$$\nabla \log p\left(\mathbf{x}_{t} \mid y\right) = \underbrace{\nabla \log p\left(\mathbf{x}_{t}\right)}_{\text{unconditional score}} + \gamma \underbrace{\nabla \log p\left(y \mid \mathbf{x}_{t}\right)}_{\text{adversarial gradient}}$$

1-4. Conditional Diffusion Model

How to guide the diffusion model under certain condition?

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How to guide the diffusion model under certain condition?

- (2) Classifier-free guidance (CFG): w/o classifier

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1-4. Conditional Diffusion Model

How to guide the diffusion model under certain condition?

- (2) Classifier-free guidance (CFG): w/o classifier

$$\nabla \log p\left(\mathbf{x}_{t} \mid y\right) = \underbrace{\nabla \log p\left(\mathbf{x}_{t}\right)}_{\text{unconditional score}} + \gamma \underbrace{\nabla \log p\left(y \mid \mathbf{x}_{t}\right)}_{\text{adversarial gradient}} \rightarrow \underbrace{\gamma \underbrace{\nabla \log p\left(y \mid \mathbf{x}_{t}\right)}_{\text{adversarial gradient}}} = \nabla \log p\left(\mathbf{x}_{t} \mid y\right) - \underbrace{\nabla \log p\left(\mathbf{x}_{t} \mid y\right)}_{\text{unconditional score}} + \underbrace{\nabla \log p\left(\mathbf{x}_{t} \mid y\right)}_{\text{unconditional score}} + \underbrace{\nabla \log p\left(y \mid \mathbf{x}_{t}\right)}_{\text{adversarial gradient}} + \underbrace{\nabla \log p\left(y \mid \mathbf{x}_{t}\right)}_{\text{unconditional score}} + \underbrace{\nabla \log p\left(\mathbf{x}_{t} \mid y\right)}_{\text{unconditional score}} + \underbrace{\nabla \log p\left(y \mid \mathbf{x}_{t}\right)}_{\text{unconditional score}} + \underbrace{\nabla \log p\left(y \mid \mathbf$$

$$\nabla \log p \left(\mathbf{x}_{t} \mid y\right) = \nabla \log p \left(\mathbf{x}_{t}\right) + \gamma \left(\nabla \log p \left(\mathbf{x}_{t} \mid y\right) - \nabla \log p \left(\mathbf{x}_{t}\right)\right)$$

$$= \nabla \log p \left(\mathbf{x}_{t}\right) + \gamma \nabla \log p \left(\mathbf{x}_{t} \mid y\right) - \gamma \nabla \log p \left(\mathbf{x}_{t}\right)$$

$$= \underbrace{\gamma \nabla \log p \left(\mathbf{x}_{t} \mid y\right) + \underbrace{(1 - \gamma) \nabla \log p \left(\mathbf{x}_{t}\right)}_{\text{unconditional score}}}_{\text{unconditional score}}$$

No need for an extra classifier!

1-4. Conditional Diffusion Model

How to guide the diffusion model under certain condition?

- (2) Classifier-free guidance (CFG): w/o classifier

```
Algorithm 1 Joint training a diffusion model with classifier-free guidanceRequire: p_{uncond}: probability of unconditional training1: repeat2: (\mathbf{x}, \mathbf{c}) \sim p(\mathbf{x}, \mathbf{c}) > Sample data with conditioning from the dataset3: \mathbf{c} \leftarrow \varnothing with probability p_{uncond} > Randomly discard conditioning to train unconditionally4: \lambda \sim p(\lambda) > Sample log SNR value5: \epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})> Corrupt data to the sampled log SNR value7: Take gradient step on \nabla_{\theta} \| \epsilon_{\theta}(\mathbf{z}_{\lambda}, \mathbf{c}) - \epsilon \|^2 > Optimization of denoising model8: until converged
```

Integrate condition inside the diffusion model!

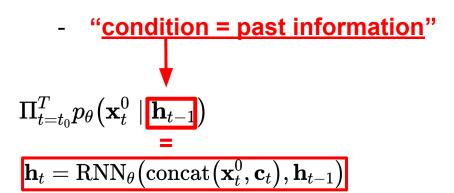
2. Conditional Time-series Diffusion Model: TimeGrad, CSDI

Conditional Time-series Diffusion Model

- TimeGrad (ICML 2021): TS Forecasting
- CSDI (NeurIPS 2021): TS Imputation

2-1. TimeGrad (ICML 2021)

- Diffusion model for TS forecasting
- Conditional diffusion model



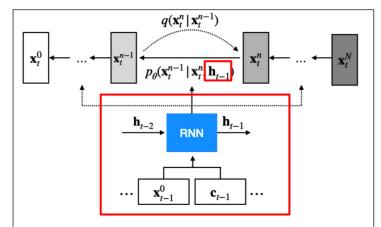
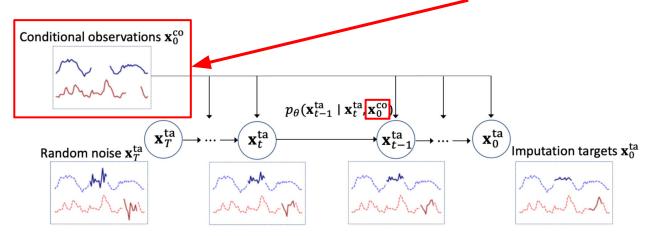


Figure 1. TimeGrad schematic: an RNN conditioned diffusion probabilistic model at some time t-1 depicting the fixed forward process that adds Gaussian noise and the learned reverse processes.

2-2. CSDI (NeurIPS 2021)

- Diffusion model for TS imputation
- Conditional diffusion model, where "condition = observed values"



2-2. CSDI (NeurIPS 2021)

Inspired by masked modeling

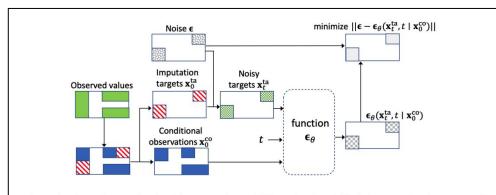


Figure 2: The self-supervised training procedure of CSDI. On the middle left rectangle, the green and white areas represent observed and missing values, respectively. The observed values are separated into red imputation targets \mathbf{x}_0^{ta} and blue conditional observations \mathbf{x}_0^{co} , and used for training of ϵ_{θ} . The colored areas in each rectangle mean the existence of values.

Masked certain portion of data for training!

- (1) Observed (= Train)
 - (1-1) unmasked (= Train X)
 - (1-2) masked (= Train Y)
 - (2) Unobserved (= Test)

Model: TSDiff

- (Previous works) Conditional model
 - condition depends on the task! (i.e. imputation, forecasting ...)
- Task-agnostic & Unconditional diffusion model for TS
- Self-guidance mechanism
 - enables conditioning for downstream tasks "during inference"
 - does not require auxiliary network or altering the training procedure

- Three tasks
 - (1) Forecasting
 - (2) Refinement
 - refine the predictions of base forecasters efficiently
 - (3) Synthetic data generation
 - train downstream forecasters using synthetic samples generated from TSDiff

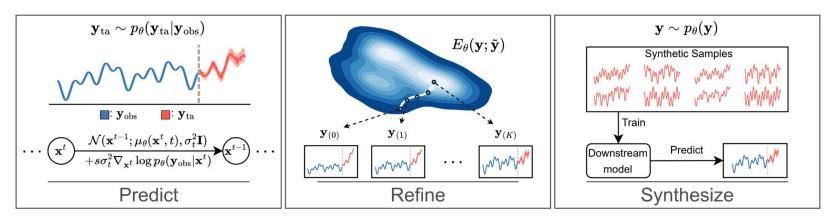


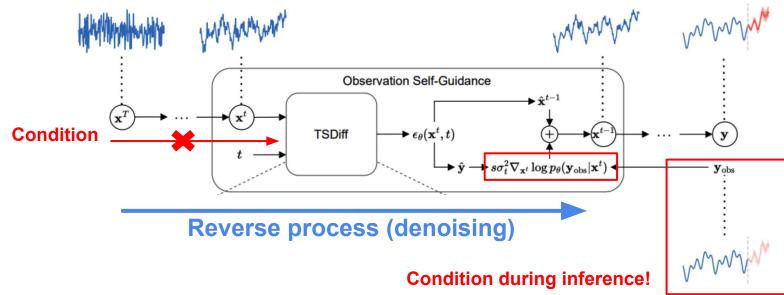
Figure 1: An overview of TSDiff's use cases. **Predict**: By utilizing observation self-guidance, TSDiff can be conditioned during inference to perform predictive tasks such as forecasting (see Sec. 3.1). **Refine**: Predictions of base forecasters can be improved by leveraging the implicit probability density of TSDiff (see Sec. 3.2). **Synthesize**: Realistic samples generated by TSDiff can be used to train downstream forecasters achieving good performance on real test data (see Sec. 4.3).

```
x_0 = 시계열
x_0 -> t번 노이즈를 부과 -> x_t
x_t -> 1번 노이즈를 부과 (=eps)-> x_{t+1}
```

$$f(x_{t+1}, t+1) = eps$$

TSDiff (NeurIPS 2023)

1) Self-Guidance



TSDiff (NeurIPS 2023)

1) Self-Guidance

for t = T to 1 do

end for

Seek to train a single unconditional generative model, $p_{\theta}(\mathbf{y})$ & Condition it during inference to draw samples $p_{\theta}(\mathbf{y}_{\mathrm{ta}} \mid \mathbf{y}_{\mathrm{obs}})$.

Algorithm 1 Observation Self-Guidance

Input: observation $\mathbf{y}_{\mathrm{obs}}$, scale s $\mathbf{x}^T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

 $\mathbf{x}^{t-1} \sim \mathcal{N}([\mu_{\theta}(\mathbf{x}^t, t)] \mathbf{I}) + s\sigma_t^2 \nabla_{\mathbf{x}^t} \log p(\mathbf{y}_{\text{obs}} | \mathbf{x}^t)$

```
1. Preliminaries: Diffusion Model
                                                                                   \nabla \log p\left(\mathbf{x}_{t} \mid y\right) = \nabla \log \left(\frac{p\left(\mathbf{x}_{t}\right)p\left(y \mid \mathbf{x}_{t}\right)}{p\left(y \mid \mathbf{x}_{t}\right)}\right)
1-4. Conditional Diffusion Model
How to guide the diffusion model under certain condition?
                                                                                                           = \nabla \log p(\mathbf{x}_t) + \nabla \log p(y \mid \mathbf{x}_t) - \nabla \log p(y)
                                                                                                                                          \nabla \log p \left(y \mid \mathbf{x}_{t}\right)
                                                                                                                 \nabla \log p\left(\mathbf{x}_{t}\right)
        (1) Classifier guidance (CG): w/ classifier
                                                                                                               unconditional score
                                                                                                                                           adversarial gradient
         Algorithm 1 Classifier guided diffusion sampling, given a diffusion model \mu_{\theta}(x_t), \Sigma_{\theta}(x_t), classi-
         fier p_{\phi}(y|x_t), and gradient scale s.
             Input: class label y, gradient scale s
             x_T \leftarrow \text{sample from } \mathcal{N}(0, \mathbf{I})
             for all t from T to 1 do
                                                                    Guidance
                \mu, \Sigma \leftarrow \mu_{\theta}(x_t), \Sigma_{\theta}(x_t)
                x_{t-1} \leftarrow \text{sample from } \mathcal{N}(\mu + s\Sigma \nabla_{x_t} \log p_{\phi}(y|x_t), \Sigma)
             end for
             return x_0
```

TSDiff (NeurIPS 2023)

1) Self-Guidance

end for

Seek to train a single unconditional generative model, $p_{ heta}(\mathbf{y})$

& Condition it during inference to draw samples $p_{ heta}\left(\mathbf{y}_{\mathrm{ta}}\mid\mathbf{y}_{\mathrm{obs}}\right)$.

Algorithm 1 Observation Self-Guidance

Input: observation $\mathbf{y}_{\mathrm{obs}}$, scale s $\mathbf{x}^T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ for t = T to 1 do $\mathbf{x}^{t-1} \sim \mathcal{N}(\mu_{\theta}(\mathbf{x}^t, t) | \mathbf{I}) + s\sigma_t^2 \nabla_{\mathbf{x}^t} \log p(\mathbf{y}_{\mathrm{obs}} | \mathbf{x}^t)$

(1) Mean Square guidance

$$p_{ heta}\left(\mathbf{y}_{ ext{obs}} \mid \mathbf{x}^{t}
ight) = \mathcal{N}\left(\mathbf{y}_{ ext{obs}} \mid f_{ heta}\left(\mathbf{x}^{t}, t
ight), \mathbf{I}
ight)$$

(2) Quantile guidance

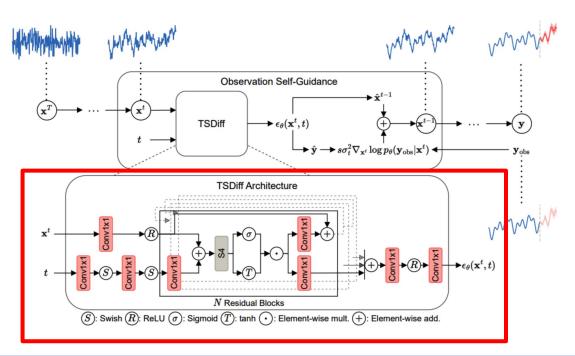
$$p_{ heta}\left(\mathbf{y}_{ ext{obs}} \mid \mathbf{x}^{t}
ight) = rac{1}{Z} \cdot \exp\left(-rac{1}{b}\max\left\{\kappa \cdot \left(\mathbf{y}_{ ext{obs}} - \boxed{f_{ heta}\left(\mathbf{x}^{t}, t
ight)}
ight), \left(\kappa - 1
ight) \cdot \left(\mathbf{y}_{ ext{obs}} - \boxed{f_{ heta}\left(\mathbf{x}^{t}, t
ight)}
ight)
ight\}$$

* Probabilistic forecasts are often evaluated using quantile-based metrics

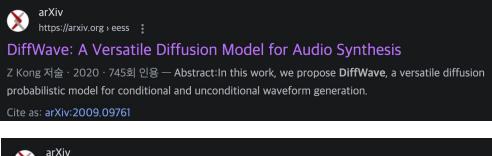
$$\hat{\mathbf{y}} = f_{ heta}\left(\mathbf{x}^t,t
ight) = rac{\mathbf{x}^t - \sqrt{(1-ar{lpha}_t)}oldsymbol{\epsilon}_{ heta}(\mathbf{x}^t,t)}{\sqrt{ar{lpha}_t}}$$

TSDiff (NeurIPS 2023)

2) Backbone



TSDiff (NeurIPS 2023) 2) Backbone - (1) DiffWave - (2) SSSD - (3) TimeDiff



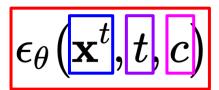
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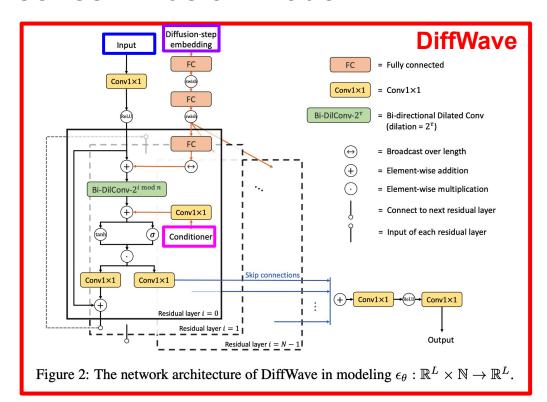
[2208.09399] Diffusion-based Time Series Imputation and ...

TSDiff (NeurIPS 2023)

2) Backbone

- (1) DiffWave
- (2) SSSD
- (3) TimeDiff

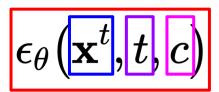


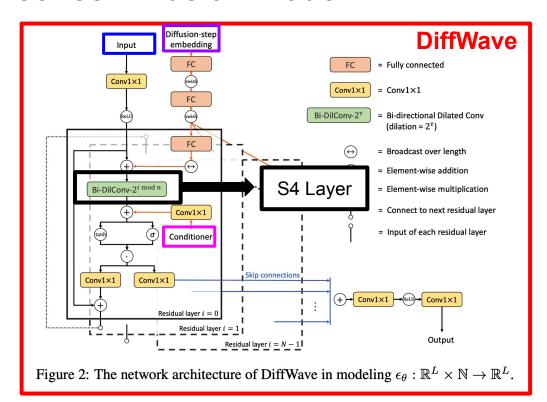


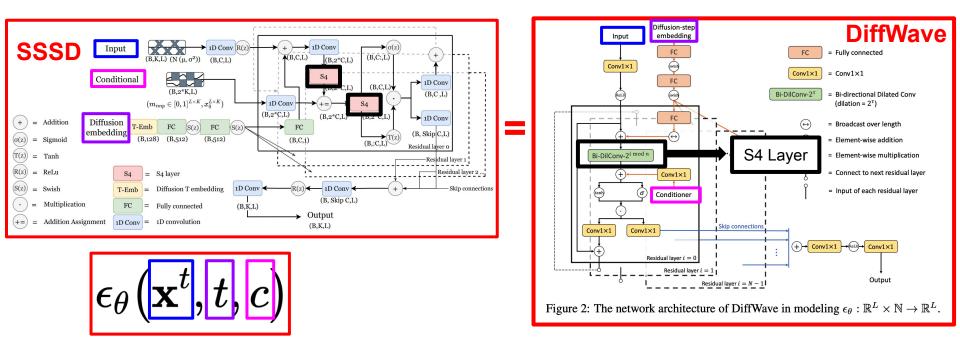
TSDiff (NeurIPS 2023)

2) Backbone

- (1) DiffWave
- (2) SSSD
- (3) TimeDiff



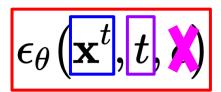


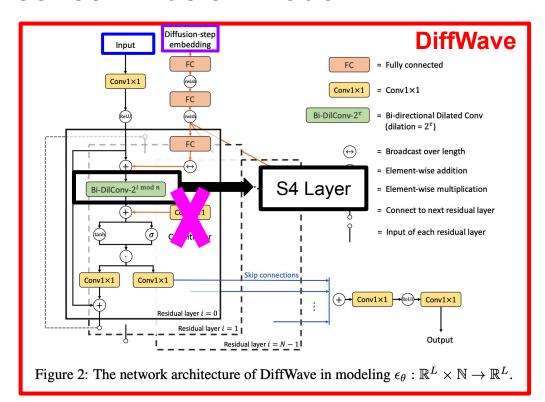


TSDiff (NeurIPS 2023)

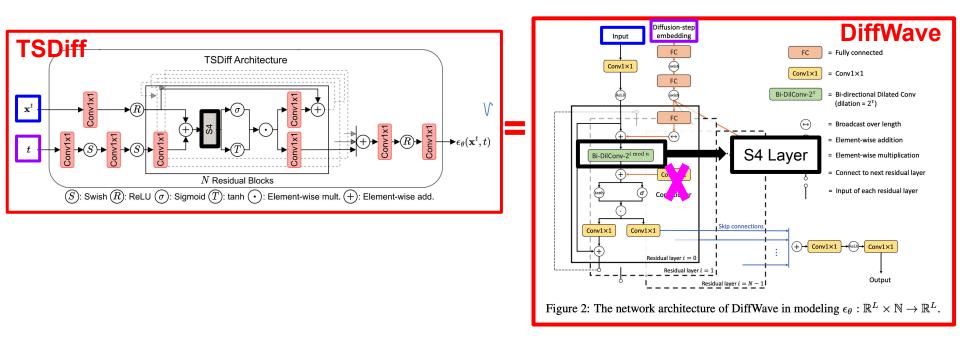
2) Backbone

- (1) DiffWave
- (2) SSSD
- (3) TimeDiff





TSDiff (NeurIPS 2023)



TSDiff (NeurIPS 2023)

2) Backbone: S4 Layer



```
Algorithm 1 S4 CONVOLUTION KERNEL (SKETCH)

Input: S4 parameters \Lambda, P, Q, B, C \in \mathbb{C}^N and step size \Delta
Output: SSM convolution kernel \overline{K} = \mathcal{K}_L(\overline{A}, \overline{B}, \overline{C}) for A = \Lambda - PQ^* (equation (5))

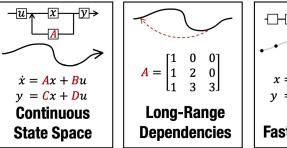
1: \widetilde{C} \leftarrow \left(I - \overline{A}^L\right)^* \overline{C} \triangleright Truncate SSM generating function (SSMGF) to length I
2: \begin{bmatrix} k_{00}(\omega) & k_{01}(\omega) \\ k_{10}(\omega) & k_{11}(\omega) \end{bmatrix} \leftarrow \begin{bmatrix} \widetilde{C} & Q \end{bmatrix}^* \left( \frac{2}{\Delta} \frac{1-\omega}{1+\omega} - \Lambda \right)^{-1} [B P] \triangleright Black-box Cauchy kerne

3: \hat{K}(\omega) \leftarrow \frac{2}{1+\omega} [k_{00}(\omega) - k_{01}(\omega)(1+k_{11}(\omega))^{-1}k_{10}(\omega)] \triangleright Woodbury Identity

4: \hat{K} = \{\hat{K}(\omega) : \omega = \exp(2\pi i \frac{k}{L})\} \triangleright Evaluate SSMGF at all roots of unity \omega \in \Omega_I

5: \overline{K} \leftarrow i \mathsf{FFT}(\hat{K}) \triangleright Inverse Fourier Transform
```

S4 = Model SSM (State-Space Model) with NN



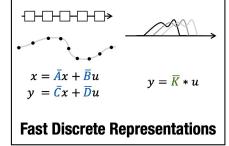


Figure 1: (Left) State Space Models (SSM) parameterized by matrices A, B, C, D map an input signal u(t) to output y(t) through a latent state x(t). (Center) Recent theory on continuous-time memorization derives special A matrices that allow SSMs to capture LRDs mathematically and empirically. (Right) SSMs can be computed either as a recurrence (left) or convolution (right). However, materializing these conceptual views requires utilizing different representations of its parameters (red, blue, green) which are very expensive to compute. S4 introduces a novel parameterization that efficiently swaps between these representations, allowing it to handle a wide range of tasks, be efficient at both training and inference, and excel at long sequences.

TSDiff (NeurIPS 2023)

3) Prediction Refinement

Goal: Refine the predictions of base forecasters

- Agnostic to the type of base forecaster
- Only assumes access to forecasts generated by them

How?

Iteratively refine the initial forecasts, using the <u>implicit density</u> learned by diffusion model (serves as a prior)

TSDiff (NeurIPS 2023)

3) Prediction Refinement

Two interpretations of refinement

- (a) Sampling from an energy function
- (b) Maximizing the likelihood to find the most likely sequence

TSDiff (NeurIPS 2023)

3) Prediction Refinement

(a) Sampling from an energy function

- Goal: draw samples from $p(\mathbf{y}_{\mathrm{ta}} \mid \mathbf{y}_{\mathrm{obs}})$
- Base forecaster g
 - Sample forecast from g : $g(\mathbf{y}_{
 m obs})$ initial guess of a sample from $p(\mathbf{y}_{
 m ta} \mid \mathbf{y}_{
 m obs})$
 - → Improve this initial guess!
- Refinement = Sampling from the regularized energy-based model (EBM)

$$E_{ heta}(\mathbf{y}; ilde{\mathbf{y}}) = \underbrace{-\log p_{ heta}(\mathbf{y})}_{ ext{Regularizer}} + \lambda \underbrace{\mathcal{R}(\mathbf{y}, ilde{\mathbf{y}})}_{ ext{Regularizer}}$$
 TS obtained by combining $\mathbf{y}_{ ext{obs}}$ and $g(\mathbf{y}_{ ext{obs}})$

Design the energy function s.t. LOW energy is assigned to samples that are LIKELY under the diffusion model

TSDiff (NeurIPS 2023)

3) Prediction Refinement

(a) Sampling from an energy function

Use overdamped Langevin Monte Carlo (LMC) to sample from this EBM

$$\mathbf{y}_{(i+1)} = \mathbf{y}_{(i)} - \eta
abla_{\mathbf{y}_{(i)}} E_{ heta}ig(\mathbf{y}_{(i)}; ilde{\mathbf{y}}ig) + \sqrt{2\eta\gamma} \xi_i \quad ext{ and } \quad \xi_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

TSDiff (NeurIPS 2023)

3) Prediction Refinement

(b) Maximizing the likelihood to find the most likely sequence

- Refinement = regularized optimization of finding the most likely TS that satisfies certain constraints

$$\argmin_{\mathbf{y}}[-\log p_{\theta}(\mathbf{y}) + \lambda \mathcal{R}(\mathbf{y}, \tilde{\mathbf{y}})]$$

TSDiff (NeurIPS 2023)

4) Experiments

Goal: Investigate whether "unconditional" TS diffusion model can be employed for downstream tasks

Three tasks

- (Predict) Probabilistic forecast (feat. Self-guidance)
- (Refine) Prediction refinement of base forecasters (feat. probability density learned by TSDiff)
- **(Synthesize)** Prediction results of downstream forecasters (feat. synthetic samples generated by TSDiff)

TSDiff (NeurIPS 2023)

4) Experiments

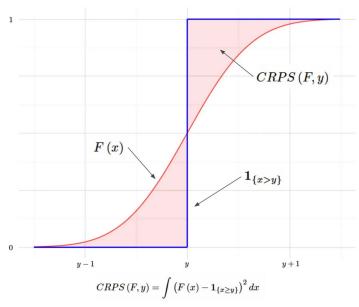
Dataset: 8 univariate TS from different domains

Metric: CRPS (Continuous ranked probability score)

 approximate CRPS by normalized average quantile loss using 100 sample paths

Table 5: Overview of the benchmark datasets used in our experiments.

Dataset	GluonTS Name	Train Size	Test Size	Domain	Freq.	Median Seq. Length	Context Length	Prediction Length
Solar	solar_nips	137	959	\mathbb{R}^+	Н	7009	336	24
Electricity	electricity_nips	370	2590	\mathbb{R}^+	H	5833	336	24
Traffic	traffic_nips	963	6741	(0, 1)	H	4001	336	24
Exchange	exchange_rate_nips	8	40	\mathbb{R}^+	D	6071	360	30
M4	m4_hourly	414	414	N	H	960	312	48
KDDCup	kdd_cup_2018_without_missing	270	270	N	H	10850	312	48
UberTLC	uber_tlc_hourly	262	262	N	H	4320	336	24
Wikipedia	wiki2000_nips	2000	10000	N	D	792	360	30



Visualization of the CRPS. The predicted distribution is marked in red, and the ground truth's degenerate distribution is marked in blue. The CRPS is the (squared) area trapped between the two CDFs. Image by author.

https://towardsdatascience.com/crps-a-scoring-function-for-bayesian-machine-learning-models-dd55a7a337a8

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4) Experiments

(Predict) Probabilistic forecast (feat. Self-guidance)

(a) Standard Forecasting

Table 1: Forecasting results on eight benchmark datasets. The best and second best models have been shown as **bold** and <u>underlined</u>, respectively.

7								
Method	Solar	Electricity	Traffic	Exchange	M4	UberTLC	KDDCup	Wikipedia
Seasonal Naive	0.512 ± 0.000	0.069 ± 0.000	0.221 ± 0.000	0.011 ± 0.000	0.048 ± 0.000	0.299 ± 0.000	0.561 ± 0.000	0.410 ± 0.000
ARIMA	0.545 ± 0.006	-	-	0.008 ± 0.000	0.044 ± 0.001	0.284 ± 0.001	0.547 ± 0.003	-
ETS	0.611 ± 0.040	0.072 ± 0.004	0.433 ± 0.050	$\overline{0.008\pm0.000}$	0.042 ± 0.001	0.422 ± 0.001	0.753 ± 0.008	0.715 ± 0.002
Linear	0.569 ± 0.021	0.088 ± 0.008	0.179 ± 0.003	0.011 ± 0.001	0.039 ± 0.001	0.360 ± 0.023	0.513 ± 0.011	1.624 ± 1.114
DeepAR	0.389±0.001	0.054±0.000	0.099±0.001	0.011±0.003	0.052±0.006	0.161±0.002	0.414±0.027	0.231±0.008
MQ-CNN	0.790 ± 0.063	0.067 ± 0.001	-	0.019 ± 0.006	0.046 ± 0.003	0.436 ± 0.020	0.516 ± 0.012	0.220 ± 0.001
DeepState	0.379 ± 0.002	0.075 ± 0.004	0.146 ± 0.018	0.011 ± 0.001	0.041 ± 0.002	0.288 ± 0.087	-	0.318 ± 0.019
Transformer	0.419 ± 0.008	0.076 ± 0.018	0.102 ± 0.002	0.010 ± 0.000	0.040 ± 0.014	0.192 ± 0.004	0.411 ± 0.021	0.214 ± 0.001
TFT	0.417 ± 0.023	0.086 ± 0.008	0.134 ± 0.007	0.007 ± 0.000	0.039 ± 0.001	0.193 ± 0.006	0.581 ± 0.053	0.229 ± 0.006
CSDI	0.352±0.005	0.054±0.000	0.159±0.002	0.033±0.014	0.040±0.003	0.206±0.002	0.318±0.002	0.289±0.017
TSDiff-Cond	0.338 ± 0.014	0.050 ± 0.002	$0.094 {\pm} 0.003$	0.013 ± 0.002	0.039 ± 0.006	0.172 ± 0.008	0.754 ± 0.007	0.218 ± 0.010
TSDiff-MS	0.391±0.003	0.062±0.001	0.116±0.001	0.018±0.003	0.045±0.000	0.183±0.007	0.325±0.028	0.257±0.001
TSDiff-Q	0.358 ± 0.020	0.049 ± 0.000	0.098 ± 0.002	0.011 ± 0.001	$0.036 {\pm} 0.001$	0.172 ± 0.005	0.311 ± 0.026	0.221 ± 0.001

TSDiff-Cond: conditional model version

TSDiff-MS: Self-guidance of MSE

TSDiff-Q: Self-guidance of Quantile Loss

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(Predict) Probabilistic forecast (feat. Self-guidance)

(b) Forecasting with missing values

Table 2: Forecasting with missing values results on six benchmark datasets.

	Method	Solar	Electricity	Traffic	Exchange	UberTLC	KDDCup
RM	TSDiff-Cond TSDiff-Q	0.357 ± 0.023 0.387 ± 0.015	0.052 ± 0.001 0.052 ± 0.001	0.097 ± 0.003 0.110 ± 0.004	0.012 ± 0.004 0.013 ± 0.000	$0.180\pm0.015 \\ 0.183\pm0.002$	0.757 ± 0.024 0.397 ± 0.042
BM-B	TSDiff-Cond	0.377±0.017	0.049±0.001	0.094±0.005	0.009±0.000	0.181±0.009	0.699±0.009
	TSDiff-Q	0.387±0.019	0.051±0.000	0.110±0.006	0.011±0.001	0.182±0.004	0.441±0.096
ВМ-Е	TSDiff-Cond	0.376±0.036	0.065±0.003	0.123±0.023	0.035±0.021	0.179±0.013	0.819±0.033
	TSDiff-Q	0.435±0.113	0.068±0.009	0.139±0.013	0.020±0.001	0.183±0.005	0.344±0.012

Missingness: masking 50%

Three scenarios

- (1) random missing (RM)
- (2) blackout missing at the beginning of input (BM-B)
- (3) blackout missing at the end of input (BM-E)

TSDiff-Q performs competitively against task-specific conditional models!

→ Robustness w.r.t missing values during inference

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(Refine) Prediction refinement of base forecasters (feat. probability density learned by TSDiff)

Table 3: Refinement results on eight benchmark datasets. The best and second best settings have been shown as **bold** and underlined, respectively.

	Setting	Solar	Electricity	Traffic	Exchange	M4	UberTLC	KDDCup	Wikipedia
Seasonal Naive	Base	0.512 ± 0.000	0.069 ± 0.000	0.221 ± 0.000	0.011 ± 0.000	0.048 ± 0.000	0.299±0.000	0.561 ± 0.000	0.410 ± 0.000
	LMC-MS	0.480 ± 0.009	0.059 ± 0.004	0.126 ± 0.001	0.013 ± 0.001	0.040 ± 0.002	0.186 ± 0.005	0.505 ± 0.027	0.339 ± 0.001
	LMC-Q	0.480 ± 0.007	0.051 ± 0.001	0.134 ± 0.004	0.009 ± 0.000	0.036 ± 0.001	0.204 ± 0.007	0.399 ± 0.003	0.357 ± 0.001
on	ML-MS	0.489 ± 0.007	0.064 ± 0.006	0.130 ± 0.002	0.015 ± 0.002	0.046 ± 0.003	0.202 ± 0.004	0.519 ± 0.028	0.349 ± 0.001
Seas	ML-Q	0.480 ± 0.007	0.050 ± 0.001	0.135 ± 0.004	0.009 ± 0.000	0.036 ± 0.001	0.215 ± 0.008	0.403 ± 0.003	0.365 ± 0.001
•,	Base	0.569±0.021	0.088 ± 0.008	0.179±0.003	0.011±0.001	0.039±0.001	0.360±0.023	0.513±0.011	1.624±1.114
=	LMC-MS	0.494 ± 0.019	0.059 ± 0.004	0.113 ± 0.001	0.013 ± 0.001	0.040 ± 0.002	0.187 ± 0.007	0.458 ± 0.015	1.315 ± 0.992
Linear	LMC-Q	0.516 ± 0.020	0.055 ± 0.003	0.119 ± 0.002	0.009 ± 0.000	0.034 ± 0.001	0.228 ± 0.010	0.346 ± 0.010	1.329 ± 1.002
I	ML-MS	0.503 ± 0.016	0.063 ± 0.005	0.117 ± 0.002	0.015 ± 0.002	0.045 ± 0.003	0.203 ± 0.007	0.472 ± 0.015	1.327 ± 0.993
	ML-Q	0.523 ± 0.021	0.056 ± 0.003	0.121 ± 0.003	0.010 ± 0.001	$0.032 {\pm} 0.001$	0.240 ± 0.010	0.350 ± 0.011	$\overline{1.335\pm1.002}$
	Base	0.389 ± 0.001	0.054 ± 0.000	0.099 ± 0.001	0.011 ± 0.003	0.052±0.006	0.161 ± 0.002	0.414±0.027	0.231 ± 0.008
DeepAR	LMC-MS	0.398 ± 0.004	0.059 ± 0.004	0.111 ± 0.001	0.012 ± 0.001	0.040 ± 0.002	0.184 ± 0.005	0.469 ± 0.034	0.227 ± 0.002
/da	LMC-Q	0.388 ± 0.002	0.053 ± 0.001	0.101 ± 0.001	0.010 ± 0.001	0.035 ± 0.001	0.161 ± 0.002	0.401 ± 0.021	0.220 ± 0.005
ã	ML-MS	0.402 ± 0.009	0.064 ± 0.006	0.115 ± 0.002	0.014 ± 0.001	0.046 ± 0.003	0.198 ± 0.005	0.477 ± 0.034	0.235 ± 0.002
	ML-Q	$0.386{\pm}0.002$	0.052 ± 0.001	0.099 ± 0.001	0.010 ± 0.002	0.035 ± 0.001	0.160 ± 0.002	0.401 ± 0.021	0.221 ± 0.006
12	Base	0.419±0.008	0.076±0.018	0.102±0.002	0.010±0.000	0.040±0.014	0.192±0.004	0.411±0.021	0.214±0.001
Ĕ	LMC-MS	0.415 ± 0.009	0.059 ± 0.004	0.111 ± 0.001	0.013 ± 0.001	0.040 ± 0.002	0.185 ± 0.005	0.462 ± 0.014	0.229 ± 0.003
Transformer	LMC-Q	0.415 ± 0.008	$\overline{0.058 \pm 0.003}$	0.101 ± 0.001	0.010 ± 0.000	0.038 ± 0.006	0.177 ± 0.005	0.384 ± 0.005	0.211 ± 0.002
an	ML-MS	0.418 ± 0.010	0.063 ± 0.005	$\overline{0.115\pm0.002}$	0.014 ± 0.002	0.046 ± 0.003	0.198 ± 0.005	0.470 ± 0.014	$\overline{0.238\pm0.003}$
H	ML-Q	0.413 ± 0.008	0.059 ± 0.005	0.099 ± 0.001	0.010 ± 0.000	0.037 ± 0.006	0.177 ± 0.005	0.384 ± 0.006	0.210 ± 0.002

Base: initial forecast

(method) LMC vs. ML

- **LMC**: Langevin Monte Carlo

ML: Maximum Likelihood

(regularize) MS vs. Q

- MS: MSE

Q: Quantile loss

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4) Experiments

(Synthesize) Prediction results of downstream forecasters (feat. synthetic samples generated by TSDiff)

- Q) How to evaluate the quality of generated samples?
- A) Several metrics have been proposed

But this paper focuses on "predictive metrics"

-> proposes Linear Predictive Score (LPS)

Test CRPS of linear (ridge) regression model trained on synthetic samples.

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4) Experiments

(Synthesize) Prediction results of downstream forecasters (feat. synthetic samples generated by TSDiff)

Table 4: Results of forecasters trained on synthetic samples from different generative models on eight benchmark datasets. Best scores are shown in **bold**.

	Generator	Solar	Electricity	Traffic	Exchange	M4	UberTLC	KDDCup	Wikipedia
	Real	0.569 ± 0.021	0.088 ± 0.008	0.179 ± 0.003	0.011 ± 0.001	0.039 ± 0.001	0.360 ± 0.023	0.513 ± 0.011	1.624 ± 1.114
Linear (LPS)	TimeVAE TimeGAN TSDiff	0.933±0.147 1.140±0.583 0.581 ± 0.032	0.128±0.005 0.234±0.064 0.065 ± 0.002	0.236±0.010 0.398±0.092 0.164 ± 0.002	0.024±0.004 0.011±0.000 0.012±0.001	0.074±0.003 0.140±0.053 0.045 ± 0.007	0.354±0.020 0.665±0.104 0.291 ± 0.084	1.020±0.179 0.713±0.009 0.481 ± 0.013	0.643 ± 0.068 0.421 ± 0.023 0.392 ± 0.013
~	Real	0.389 ± 0.001	0.054 ± 0.000	0.099 ± 0.001	0.011 ± 0.003	0.052 ± 0.006	0.161 ± 0.002	0.414 ± 0.027	0.231 ± 0.008
DeepAR	TimeVAE TimeGAN TSDiff	0.493±0.012 0.976±0.739 0.478 ± 0.007	0.060±0.001 0.183±0.036 0.058 ± 0.001	0.155 ± 0.006 0.419 ± 0.122 0.129 ± 0.003	0.009±0.000 0.008±0.001 0.017±0.009	0.039±0.010 0.121±0.035 0.042±0.024	0.278±0.009 0.594±0.125 0.191 ± 0.018	0.621±0.003 0.690±0.091 0.378 ± 0.012	0.440 ± 0.012 0.322 ± 0.048 0.222 ± 0.005
Transf.	Real	0.419±0.008	0.076±0.018	0.102±0.002	0.010 ± 0.000	0.040±0.014	0.192±0.004	0.411±0.021	0.214±0.001
	TimeVAE TimeGAN TSDiff	0.520±0.030 0.972±0.687 0.457 ± 0.008	0.071±0.009 0.182±0.008 0.056 ± 0.001	0.163±0.018 0.413±0.204 0.143 ± 0.020	0.011±0.001 0.009±0.001 0.030±0.021	0.035±0.011 0.114±0.052 0.030±0.008	0.291±0.008 0.685±0.448 0.225 ± 0.055	0.717±0.181 0.632±0.016 0.356 ± 0.030	0.451±0.017 0.314±0.045 0.239±0.010

Even performs better than the model trained with REAL data!

4. Conclusion

4. Conclusion

- Diffusion model with TS has not been widely explored yet.
 (Most of the work has been done in computer vision domain)
- All the previous works (except for TSDiff) uses "conditional" diffusion model
- "Unconditional" diffusion model is task-agnostic, imposing condition during inference
- Future work: develop unconditional TS diffusion model...
 - with model architecture tailored for TS data
 (i.e. Temporal dependency, Time series decomposition)
 - with noise scheduling tailored for TS data
 (i.e. exploring ACF(auto-correlation function))

References

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Thank You!

